* + in concept of operation ; explain what a user would be doing,
  + explain more on how the system is going to be tested. how are we sure it "works"
  + there is 3rd input, hardware should take in GPS coordinates and output that IF the other 2 are verified
  + make block diagram
  + gps verifies where it SHOULD be.
  + decides what limits should be placed, should not allow an intruder to continuously attempt to break in. separate limit from pin and voice
  + should create a "shutdown" in which it should keep them out if there are many continuous failures
  + if laptop can't receive gps, need separate module
  + GPS should be outputted in latitude longitude ; only outputted is needed, no need to do anything with it
  + frequency range do 200 20khz
  + for regular speech, 100 to 4k can work
  + male can reach up to 10k and woman up to 15k
  + comparing graphs. there are some clear differences
    - tamarr 550, 130, 250
    - navid 490 600 ,100
  + find tolerance by finding how much the frequencies vary between each member's ranges
  + compare frequencies NOT MAGNITUDE
  + sort highest frequencies to lowest
  + read through the error analysis in the thesis that was sent out
  + make new figures ; scale plots up to 2500hz
  + say "hello python", "this is [my name]" "this is [other member's name]" three times, total 9 plots